

## Definition

When you solve a system  $\mathbf{x}' = \mathbf{A}\mathbf{x}$  then your solution is

$$\mathbf{x}(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

The phase plane is plotting the solutions  $(x_1(t), x_2(t))$  as  $x_2 = f(x_1)$ .

## Equilibrium

A **fixed point** is  $\mathbf{x}$  such that  $\mathbf{x}' = \mathbf{0} \implies \mathbf{A}\mathbf{x} = \mathbf{0}$ .

When  $\mathbf{A}$  is invertible (i.e.  $\det(\mathbf{A}) \neq 0$ ), the system  $\mathbf{x}' = \mathbf{A}\mathbf{x}$  has one fixed point  $\mathbf{x} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

## Classification of Equilibrium at (0,0)

- Distinct real eigenvalues:  $\lambda_1 \neq \lambda_2$ 
  - $\lambda_1 > 0, \lambda_2 > 0 \implies$  **source point, unstable**
  - $\lambda_1 \cdot \lambda_2 < 0 \implies$  **saddle, unstable**
  - $\lambda_1 < 0, \lambda_2 < 0 \implies$  **sink node, asymptotically stable**
- Complex conjugate eigenvalues:  $\lambda_1 = \alpha + i\beta$  and  $\lambda_2 = \alpha - i\beta$ .
  - $\alpha = 0 \implies$  **center, stable (but not asymptotically)**
  - $\alpha < 0 \implies$  **spiral point, asymptotically stable**
  - $\alpha > 0 \implies$  **spiral point, unstable**
- Repeated real eigenvalue:  $\lambda = \lambda_1 = \lambda_2$ .  
If you have two eigenvectors
  - $\lambda > 0 \implies$  **proper node, unstable**
  - $\lambda < 0 \implies$  **proper node, asymptotically stable**

otherwise

- $\lambda > 0 \implies$  **improper node, unstable**
- $\lambda < 0 \implies$  **improper node, asymptotically stable**

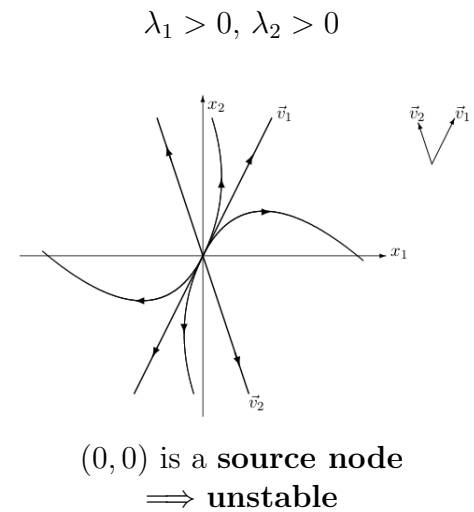
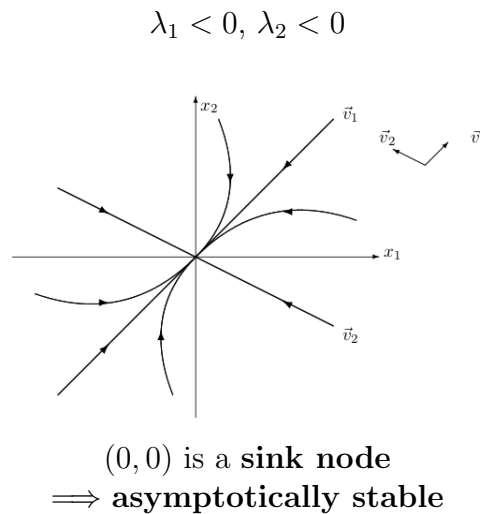
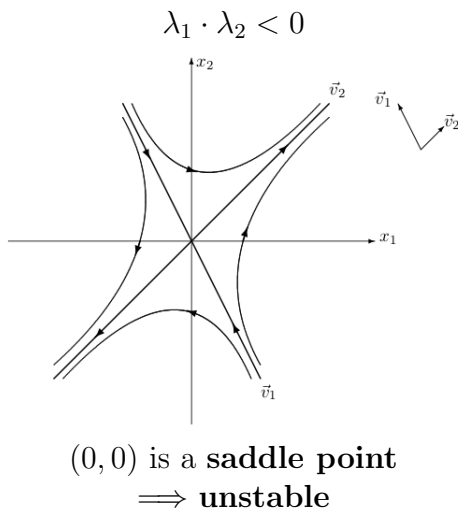
# Phase plane

The system is

$$\mathbf{x}' = \mathbf{A}\mathbf{x}$$

**Distinct real eigenvalues:**  $\lambda_1 \neq \lambda_2$ , then the general solution is

$$\mathbf{x} = C_1 e^{\lambda_1 t} \mathbf{v}_1 + C_2 e^{\lambda_2 t} \mathbf{v}_2$$

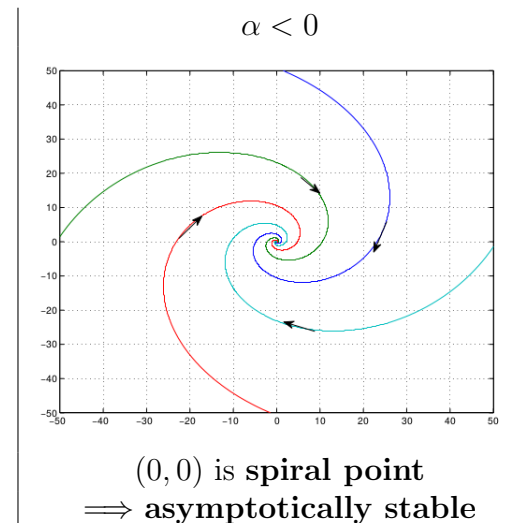
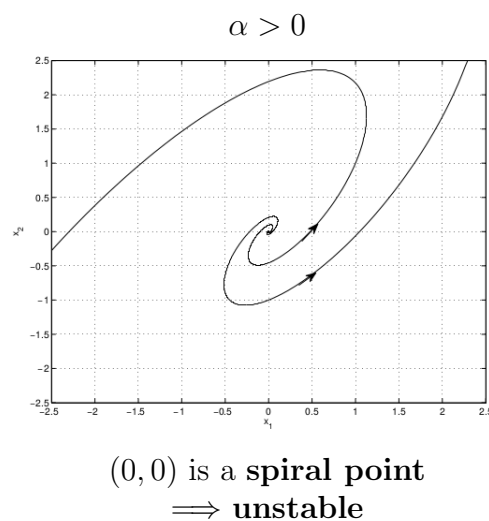
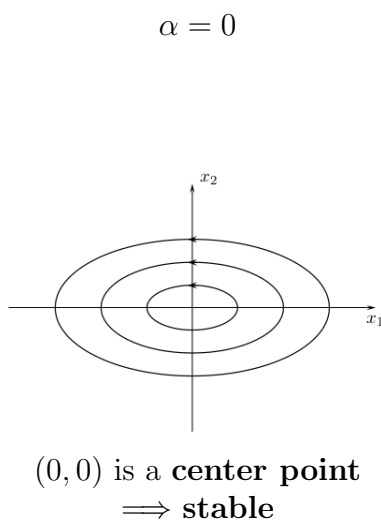


**Complex conjugate eigenvalues:**  $\lambda_1 = \alpha + i\beta$  and  $\lambda_2 = \alpha - i\beta$ . Then the eigenvectors are  $\mathbf{v}_1 = \mathbf{a} + i\mathbf{b}$  and  $\mathbf{v}_2 = \mathbf{a} - i\mathbf{b}$ , and the general solution is

$$\mathbf{x} = C_1 e^{\alpha t} [\cos(\beta t)\mathbf{a} - \sin(\beta t)\mathbf{b}] + C_2 e^{\alpha t} [\cos(\beta t)\mathbf{b} + \sin(\beta t)\mathbf{a}]$$

Trick to remember

$$\mathbf{x} = C_1 \cdot \text{Re}(e^{\lambda_1 t} \mathbf{v}_1) + C_2 \cdot \text{Im}(e^{\lambda_1 t} \mathbf{v}_1)$$



**Repeated real eigenvalue:**  $\lambda = \lambda_1 = \lambda_2$ .

If you can find two linearly independent eigenvectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$

$$\mathbf{x} = C_1 e^{\lambda t} \mathbf{v}_1 + C_2 e^{\lambda t} \mathbf{v}_2$$

If not, take  $\mathbf{v}$  eigenvector associated to  $\lambda$

$$\mathbf{x} = C_1 e^{\lambda t} \mathbf{v} + C_2 (te^{\lambda t} \mathbf{v} + e^{\lambda t} \boldsymbol{\eta})$$

where  $\boldsymbol{\eta}$  solves  $(\mathbf{A} - \lambda \mathbf{I})\boldsymbol{\eta} = \mathbf{v}$

If there are two linearly independent eigenvector	
$\lambda < 0$ $(0, 0)$ is an <b>proper node</b> $\implies$ <b>asymptotically stable</b>	$\lambda > 0$ $(0, 0)$ is an <b>proper node</b> $\implies$ <b>unstable</b>
If there is only one linearly independent eigenvector	
$\lambda < 0$ $(0, 0)$ is an <b>improper node</b> $\implies$ <b>asymptotically stable</b>	$\lambda > 0$ $(0, 0)$ is an <b>improper node</b> $\implies$ <b>unstable</b>